

# Gabor Based Face Recognition Using EBGM and PCA

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**ABSTRACT-** Face recognition has received substantial attention in recent years due to applications in Research fields such as biometrics community and computer vision. A lot of face recognition algorithms have been developed during the past decades. These algorithms can be classified into appearance-based and model-based schemes. Principal Component Analysis (PCA) is a typical linear appearance-algorithm, and Elastic Bunch Graph Matching (EBGM) is a two-dimensional model-based approach. This paper reviews the two classical methods and a typical face image database for standard testing.

In many applications of Face recognition, the best possible accuracy is required. In such circumstances, existing efficient algorithms do not guarantee good accuracy for the approximations they produce. We propose an efficient algorithm that recognizes novel faces by first localizing a set of landmark features, Approximates the landmark features, and then measuring similarity between these features. For the first approach we use feature based algorithm called as EBGM (Elastic bunch graph matching). For the second approach we use the statistical based algorithm called as PCA (Principal component analysis). The algorithms are implemented on Matlab environment. Scenarios and performance benchmarking are compared for each of the algorithms.

**KEYWORDS:** Face recognition, PCA, EBGM, landmark features, Jets.

## INTRODUCTION

Machine recognition of Face is emerging as an active research area spanning several disciplines such as image processing, pattern recognition, computer vision and neural network. Research interest in face recognition has grown significantly in recent years as a result of facts such as the increase in emphasis on civilian/commercial research projects, the increasing need for surveillance related application due to drug trafficking, terrorist activities etc., and the availability of real time hardware. [13]

Most of the conventional access control systems have the following drawbacks: these systems do not grant access by "who we are", but by "what we have", such as ID cards, keys, passwords, PIN numbers. These methods require the user to remember a password, to enter a PIN CODE, to carry a badge, or in general, require a human action. The corresponding means (Key, badges, password, PIN CODE) are prone to lost or being forgotten. People are not comfortable in placing their eyes before a scanner or giving a drop of blood for DNA sequencing. Face recognition is one of the few biometric methods that possess the merits of both high accuracy and low intrusiveness.[6]

Human often use faces to recognize individuals and advancement in computing capability over the past few decades now enables similar recognition automatically. Early face recognition algorithms used simple geometric models but the recognition process has now matured into science of sophisticated mathematical representations and matching processes. Major advancements and initiatives in the past ten years have propelled face recognition technology into spot light. Face recognition can be used as both identification and recognition. (Open set and closed set).

Face detection is one of the tasks which human vision can do effortlessly. However, for computer vision, this task is not that easy. A general definition of the problem can be stated as follows: Identify all of the regions that contain a face, in a still image or image sequence, independent of any three dimensional transformation of the face and lighting condition of the scene.

The main difficulty in face recognition includes:

- 1) *Physical changes:* facial expression change; aging; personal appearance (make-up, glasses, facial hair, hairstyle, disguise).
- 2) *Acquisition geometry changes:* change in scale, location and in-plane rotation of the face (facing the camera) as well as rotation in depth (facing the camera obliquely, or presentation of a profile, not full-frontal face).
- 3) *Imaging changes:* lighting variation; camera variations; channel characteristics (Especially in broadcast or compressed images).

There are several methods used for this problem and they can be broadly classified in two main classes, which are *feature-based* and *image-based* approaches. The appearance-based algorithms can be further divided as linear and non-linear;

Previous research has shown that both feature-based and image-based approaches perform effectively while detecting upright frontal faces, whereas feature-based approaches show a better performance for the detection scenarios especially in simple scenes. In this work, two different feature based and statistical based algorithm are used for the purpose of face recognition task.

### A. *Classification of face detection Algorithms*

In image-based techniques, features are extracted without prior knowledge about the object of interest, and are typically fast and simple. In the presence of extensive pose variations,

however, these techniques can be unreliable and unmanageable.

In model-based techniques, facial features are represented as 2D models or 3D models. With 2D models, the recognition system tries to represent facial features without attempting to recover the volumetric geometry of the scene whereas in 3D face models the features are represented in 3D that gives more accurate representation of facial features. Due to complex mapping procedures, 3D models are computationally demanding.

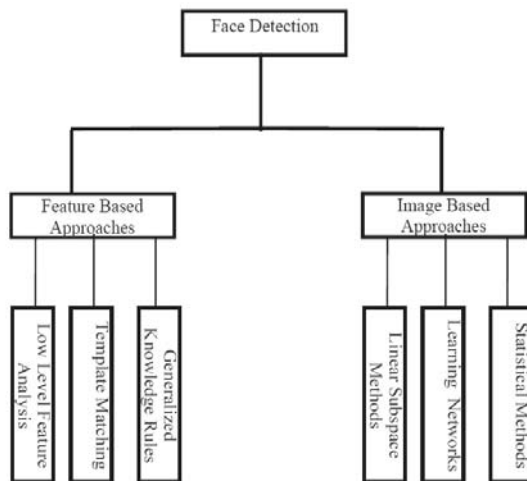


Figure 1. Classification of face detection Algorithms

### B. Statistical Techniques:

Statistical techniques rely on statistical analysis of facial features. A few of the statistical techniques that are used in face recognition are PCA, ICA and LDA.

1) *Principal Component Analysis (PCA)*: The Principal Component Analysis (PCA) [7] is one of the most successful techniques that have been used in image recognition and compression. PCA is a statistical method under the broad title of *factor analysis*. The purpose of PCA is to reduce the large dimensionality of the data space (observed variables) to the smaller intrinsic dimensionality of feature space (independent variables), which are needed to describe the data economically. This is the case when there is a strong correlation between observed variables. The jobs which PCA can do are prediction, redundancy removal, feature extraction, data compression, etc. Because PCA is a classical technique which can do something in the linear domain, applications having linear models are suitable, such as signal processing, image processing, system and control theory, communications, etc.

### 2) *Feature Based Techniques*:

Feature-based approaches, on the other hand, rely on information about well-defined facial characteristics and the image area around these points to represent a face in the problem space and perform recognition. Examples of these

facial features are the eyes, nose, mouth, eyebrows etc. The exact coordinates of the eyes in particular are ideally given, although in practice the algorithm can only work with estimates obtained from face detection and eye zone locator module that precedes the recognition process. An example of a feature-based approach is the Elastic Bunch Graph Matching (EBGM) algorithm [1, 12], which stores spectral information about the neighborhoods of facial features by convolving these areas with Gabor wavelets (masks).

### 3) *EBGM Algorithm Overview*:

EBGM algorithm is a feature-based approach [1, 2] to the face identification problem. In the context of EBGM, the facial features that are used are called fiducial points. Images are represented internally by the algorithm using spectral information of the regions around these features, which is obtained after convolving those portions of the image with a set of Gabor wavelets [5, 2] of varying size, orientation and phase. The results of the convolution for a specific position (called the Gabor Jet) are then collected for all fiducial points on a given image and aggregated (together with the feature coordinates) in that image's Face Graph. Having applied this process to all images in the training set, all the resulting Face Graphs are concatenated in a stack-like structure called the Face Bunch Graph (FBG) [5, 1]. This is the system's model of all individuals it can identify. Automatic feature localization capability is one of the major advantages of the EBGM algorithm. After the Face Graph has been constructed, it is compared against all members of the FBG to determine the closest match according to a given similarity metric.

### 4) *Landmark Locations and Features*:

EBGM algorithm is easily divided into three steps. The first step is to determine the landmark locations. A face graph is created for every image that needs to be matched. Finally, similarity of face graphs is computed and final classification is based on this similarity.

*Landmarks* [1, 12] are parts of the face that are easily located and have similar structure across all faces. Some obvious examples of landmarks are the eyes, nose, and mouth. Each of these landmarks is well defined, is common to all faces, and has distinct representations in image space. Typically landmarks are defined such that their location has a very small error tolerance. Instead of defining a landmark as the "nose", the landmark is defined as the "nose tip". The nose tip can be located to within a few pixels.

*Landmark Locations* are the pixel coordinates of landmarks. Landmark locations define the geometry of the face. An example of this is the nose tip, which has a well defined location.

*Landmark Features* are defined by the frequency information of the local regions that surround the landmark locations. A landmark jet is not a particular point but instead contains information about the pixel values surrounding the landmark location. A landmark jet refers to information on what the landmark looks like.

Gabor jets [1] are used to represent the landmark jet information in the EBGM algorithm. A Gabor jet is produced by convolving the landmark location with a collection of Gabor masks. Therefore, the Gabor jet will contain a good description of the local frequency information around the landmark.

Jet [2]: a set of 40 (5 spatial frequency, 8 orientations) complex Gabor wavelet coefficients for one image point.  $J = [a_1, a_2 \dots a_{40}]$ . Similarity between jets.

$$S_a(J, J') = \frac{J^T J'}{|J| \cdot |J'|}$$

$$S_\phi(J, J') = \frac{\sum_j a_j a'_j \cos(\phi_j - \phi'_j - \underline{d} \cdot \underline{k}_j)}{|J| \cdot |J'|}$$

$\underline{d}$  is the displacement of pixels: needs to be estimated.  $\underline{k}_j$ : spatial wave vector. The fig.2 shows the jets.

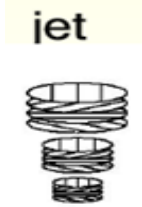


Figure 2. Jets

**METHODOLOGY**

Various approaches have been proposed in the literature for face recognition algorithms which can be classified into three categories

- ANALYTICAL(FEATURE BASED)
- HOLISTIC(GLOBAL)
- HYBRID

**A. Approach**

The proposed approach is as follows:

- Recognizes novel faces by first localizing a set of landmark features.
- Approximation of landmark features.
- And then measuring similarity between these features

For the 1<sup>st</sup> approach we use feature based algorithm called as **EBGM (Elastic bunch graph matching)**

For the 2<sup>nd</sup> approach we use the statistical based algorithm called as **PCA (Principal component analysis)**.

The methodology for the project work is carried by the use of the HYBRID approach. The difficulty in the analytic approach of EBGM is the requirement of accurate landmark localization which can be achieved by the use of holistic approach method PCA. The approach proceeds as:

**LOCALIZATION:** Recognize novel faces by first localizing a set of landmark features.

**APPROXIMATION:** Approximation of landmark features using PCA

**COMPARISION:** Measuring similarity between these features.



Figure 3. Proposed methodology

In any case, a basic goal should be to cover the face evenly; however, a large number of extra points will be detrimental to the algorithm's performance, since the areas covered by the Gabor wavelets will be overlapping and thus the information contained in the Gabor jets of neighboring points highly correlated reduces the algorithm speed.

The purpose of PCA is to reduce the large dimensionality of the data space (observed variables) to the smaller intrinsic dimensionality of feature space (independent variables), which are needed to describe the data economically. This is the case when there is a strong correlation between observed variables.

Thus we take a large number of fiducial points on the face for the process of localization, and then we can reduce the large dimensionality of the data space (observed variables) to the smaller intrinsic dimensionality of feature space by using the PCA algorithm.

**B. Proposed Algorithm**

**STEP 1:** Jets are selected by hand to serve as facial features. The following figure shows this.



Figure 4. Selection of jets

**STEP 2:** A bunch graph is created each node of the bunch graph corresponds to a facial landmark and contains a bunch of model jets extracted from model imagery.

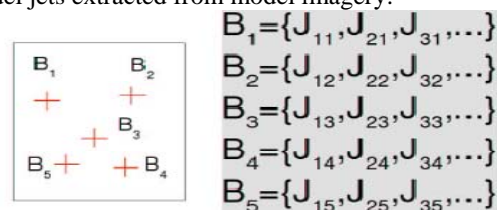


Figure 5. Creation of bunch graph

**STEP 3:** An approximation of landmarks is obtained. Let's suppose we have  $M$  facial landmarks of size  $N$  (= rows and columns) representing a set of sampled images.  $p_j$ 's represent the jet values.

$$x_i = [p1 : : : pN]T ; i = 1 : : : ;M$$

The facial landmarks are mean centered by subtracting the mean facial landmarks from each facial landmarks vector. Let  $m$  represent the mean facial landmarks

$$m = \frac{1}{M} \sum_{i=1}^M x_i$$

And let  $w_i$  be defined as mean centered facial landmarks

$$w_i = x_i - m$$

Our goal is to find a set of  $e_i$ 's which have the largest possible projection onto each of the  $w_i$ 's. We wish to find a set of  $M$  orthonormal vectors  $e_i$  for which the quantity Calculating the coefficients of the principal components and their respective variances is done by finding the eigenfunctions of the sample covariance matrix:

$$e_l^T e_k = \delta_{lk}$$

The covariance matrix is given as follows:

$$C = WW^T$$

STEP 4: After the Approximation by the principal component analysis, landmark points are located for every image. First a novel jet is extracted from the novel image; the displacement of the novel jet from actual location is estimated by comparing it with the most similar model jet from the corresponding bunch.

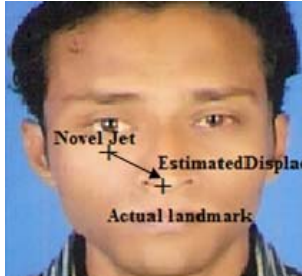


Figure 6. Novel image

STEP 5: A face graph is created for each image by extracting a jet for each landmark. The graph contains the location of the landmarks and value of the jets. The original image can then be discarded.

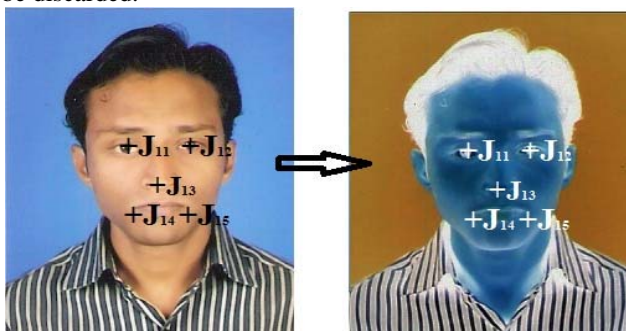


Figure 7. Extraction of jet

STEP 6: The last step consist of comparison. Face similarity is computed as a function of landmark locations and jet values

**C. Flow Diagram of proposed Algorithm**

The algorithm is divided into four executables:

Landmark localization, approximation, face graph creation, and similarity measurement. The complete system can be said to consist of five data processing steps, and there are six intermediate data types. The output of the algorithm is a distance matrix which specifies the similarity between each image in the database. The algorithm assumes that more similar images have smaller distances between them.

The complete identification processes is defined in figure 8.

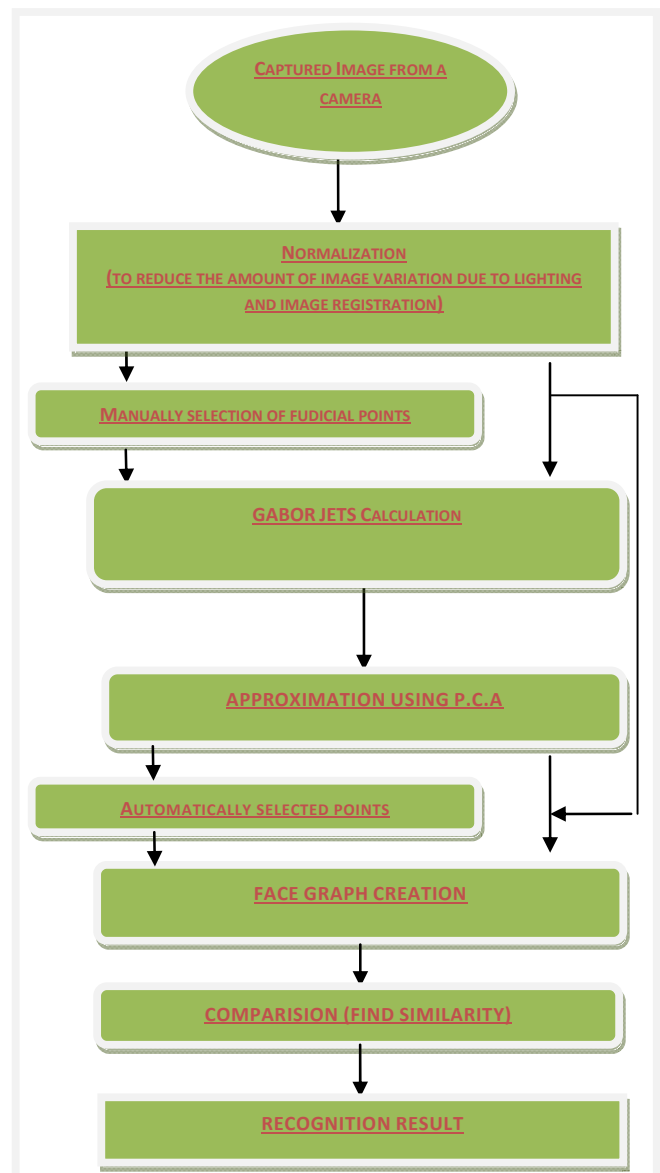


Figure 8. Flow diagram of PROPOSED ALGORITHM

### CONCLUSION

A person authentication technique using face recognition is presented where we propose an algorithm based on hybrid approach. After implementation and comparison of the two classical face recognition algorithms, PCA and EBGM, taking in consideration three main factors, total training image number, accuracy rate and processing speed, we find from the result that EBGM perform better than PCA. EBGM has the highest accuracy rate but the computational time is relative long. And if we increase the number of landmarks in EBGM the performance reduces so if we use the hybrid approach better results can be obtained. This technique is based on the extraction of jets. This concept is related to the Gabor wavelet which was introduced by Daugman in 1988. Our work will focus on combining the two algorithms for high accuracy and smaller processing time.

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